HOLDING, PROCEDURE TURNS AND MISSED APPROACHES

NOTE

Due to the sophistication of the G1000 Flight Management System (FMS), IFR enroute and instrument approach procedures using the G1000 FMS/GPS and KAP 140 Autopilot should be mastered in VFR conditions (with a safety pilot) before attempting IFR operations. Refer to the G1000 Cockpit Reference Guide for additional information.

Special consideration must be given to SUSP softkey operation and KAP 140 mode selection during holding pattern, course reversal maneuver (procedure turn) or missed approach procedures when using the G1000 FMS/GPS. The G1000 FMS/GPS provides initial entry cues for the procedure turn and the holding pattern but does not provide course guidance for either maneuver.

Holding pattern operations, whether in the enroute or the terminal environment, require temporary suspension of flight plan execution on reaching the holding waypoint. If the holding pattern is part of an Instrument Approach Procedure (IAP) without an associated Procedure Turn, suspend (SUSP) mode will be invoked automatically by the G1000 FMS/GPS on reaching the holding waypoint (usually an IAF). Holding at an enroute waypoint will require the pilot to manually suspend flight plan execution using the OBS softkey and set the course pointer to the inbound course.

CAUTION

IF THE KAP 140 AUTOPILOT IS ENGAGED IN EITHER NAV OR APR MODE WHEN THE G1000 FMS/GPS GOES TO SUSP MODE OR IF THE PILOT MANUALLY SELECTS OBS MODE, THE KAP 140 AUTOPILOT WILL BE OPERATING WITHOUT A VALID NAVIGATION SOURCE. SELECT HDG MODE FOR KAP 140 AUTOPILOT OPERATION AND CONTROL AIRCRAFT HEADING USING THE HDG CONTROL ON THE PFD (TO SET THE HSI HEADING BUG).

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HOLDING, PROCEDURE TURNS AND MISSED APPROACHES (Continued)

NOTE

If the holding waypoint is shown with a holding pattern on the MFD NAVIGATION MAP display, selecting the OBS softkey (to suspend flight plan execution) will cause the G1000 to erase the depicted holding pattern from the display.

The G1000 FMS/GPS provides course guidance on the inbound leg (toward the holding waypoint) of the holding pattern only. Turns at either end of the holding pattern and the outbound leg must be executed by the pilot manually or by setting the KAP 140 Autopilot to HDG mode and then setting the HDG bug on the PFD to command the Autopilot to turn to each new heading. The KAP 140 Autopilot may be set to APR mode to track the inbound course but must be returned to HDG mode for command through the remainder of the holding pattern.

NOTE

On interception of the inbound course for RNAV(GPS) Approach holding patterns, SUSP will be automatically deselected by the G1000 FMS/GPS. If continued holding is desired, SUSP must be manually selected before reaching the holding waypoint.

When the pilot wants to discontinue holding, either to proceed enroute or for the IAP, flight plan execution is resumed by selecting the OBS or SUSP key as appropriate.

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HOLDING, PROCEDURE TURNS AND MISSED APPROACHES (Continued)

The G1000 FMS/GPS treats the procedure turn maneuver as a flight plan leg and does not suspend (SUSP) flight plan execution at the IAF waypoint. The G1000 FMS/GPS provides an outbound heading for the procedure turn and prompts "BEGIN PROCEDURE TURN" at approximately one minute beyond the IAF. The pilot must turn away from the final approach course to start procedure turn either manually or must select the KAP 140 Autopilot HDG mode and set the HDG bug on the PFD to command the Autopilot to turn to the new heading. Following course reversal (inbound to join the final approach course), the G1000 FMS/GPS sequences to capture the final approach course. The pilot must intercept and join the final approach course manually or select the KAP 140 Autopilot APR mode to enable automatic capture the final approach course.

GPS or RNAV(GPS) approaches are managed by the G1000 FMS/GPS to provide course guidance and waypoint sequencing through the approach procedure. For ILS approaches, the G1000 FMS/GPS provides course guidance for the KAP 140 to capture the final approach course. The G1000 will tune the NAV 1 radio to the applicable facility frequency (with identifier) and set the course pointer to the final approach course. Within approximately 0.5 nm of the final approach course, the G1000 FMS/GPS will automatically change the HSI navigation source from GPS to NAV1. The change from GPS to NAV1 will make the KAP 140 change from NAV, APR or APR ARM mode to ROL mode operation and allow the airplane to fly through the final approach course, if not corrected. The pilot must manually set APR mode again to make the KAP 140 lock on the final approach course and the glideslope using the VHF NAV1 signal. If using radar vectors to navigate with the KAP 140 engaged in HDG mode to the ILS final approach course, wait until the G1000 changes the HSI navigation source to NAV1 before the KAP 140 is set to APR mode to avoid KAP 140 ROL mode reversion.

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HOLDING, PROCEDURE TURNS AND MISSED APPROACHES (Continued)

WARNING

WHEN THE KAP 140 AUTOPILOT IS ENGAGED IN NAV, APR OR REV OPERATING MODES, IF THE HSI NAVIGATION SOURCE IS CHANGED FROM **GPS TO NAV1 AUTOMATICALLY OR MANUALLY** (USING THE CDI SOFTKEY) OR MANUALLY FROM NAV2 TO GPS, THE CHANGE WILL INTERRUPT THE NAVIGATION SIGNAL TO THE **AUTOPILOT AND WILL CAUSE THE AUTOPILOT** TO REVERT TO ROL MODE OPERATION. WARNING CHIME OR PFD ANNUNCIATION IS PROVIDED. THE PREVIOUSLY SELECTED MODE SYMBOL SHOWN ON THE AUTOPILOT DISPLAY WILL BE FLASHING TO SHOW THE REVERSION TO ROL MODE OPERATION. IN ROL MODE, THE AUTOPILOT WILL ONLY KEEP THE WINGS LEVEL AND WILL NOT CORRECT THE AIRPLANE HEADING OR COURSE. SET THE HDG BUG TO THE CORRECT HEADING AND SELECT THE CORRECT NAVIGATION SOURCE ON THE HSI USING THE CDI SOFTKEY BEFORE ENGAGING THE AUTOPILOT IN ANY OTHER OPERATING MODE.

Other VHF NAV-based Instrument Approach Procedures (VOR, LOC, LOC BC) require the pilot to manually tune and identify the NAV facility, select the corresponding NAV source on the HSI and set the HSI course pointer to the final approach course. See the G1000 Cockpit Reference Guide for additional information.

On reaching the Missed Approach Point (MAP), the G1000 FMS/GPS will automatically go into suspend (SUSP) mode but will continue to provide course guidance along the extended runway centerline. After the pilot stabilizes the airplane in climb, SUSP mode may be deselected using the SUSP softkey and the G1000 FMS/GPS will provide course guidance to the Missed Approach Holding Point (MAHP). On reaching the MAHP, the pilot may elect to hold (as noted above) or may select another IAP. See the G1000 Cockpit Reference Guide for additional information.